



## Projekta Izp-2018/1-0482 rezultāti

### Notikumos sakņota datorredze lauksaimniecības robotiem

*Oriģināli zinātniskie raksti, kas publicēti zinātniskos žurnālos, rakstu krājumos vai konferenču rakstu krājumos, kuri ir indeksēti datu bāzēs Web of Science Core Collection, SCOPUS vai ERIH PLUS*

1. Zujevs, A.; Nikitenko, A. Visual navigation datasets for event-based vision: 2014-2021. - 18th International Conference on Informatics in Control, Automation and Robotics, ICINCO 2021, SciTePress: pp 507-513. <https://doi.org/10.5220/0010607105070513>
2. Osadcuks, V.; Pudzs, M.; Zujevs, A.; Pecka, A.; Ardavs, A. Clock-based time sync hronization for an event-based camera dataset acquisition platform \*. - 2020 IEEE International Conference on Robotics and Automation, ICRA 2020, Institute of Electrical and Electronics Engineers Inc.: pp 4695-4701. <https://doi.org/10.1109/ICRA40945.2020.9197303>
3. Zujevs, A.; Pudzs, M.; Osadcuks, V.; Ardavs, A.; Galauskis, M.; Grundspenkis, J. An Event-based Vision Dataset for Visual Navigation Tasks in Agricultural Environments. - 2021 IEEE International Conference on Robotics and Automation, ICRA 2021, Institute of Electrical and Electronics Engineers Inc.: Vol. 2021-May, pp 3707-3713. <https://doi.org/10.1109/ICRA48506.2021.9561741>
4. Galins, J.; Osadcuks, V.; Pecka, A. Evaluation of passive cooling system in plywood enclosure for agricultural robot prototype. - Agron. Res., 2021, 19 (Special Issue 1), 739-748, <https://doi.org/10.15159/AR.21.054>
5. Galauskis, M.; Ardavs, A. The Process of Data Validation and Formatting for an Event-Based Vision Dataset in Agricultural Environments. - Applied Computer Systems, 2021, 26 (2), 173-177, <https://doi.org/10.2478/acss-2021-0021>

